# Stochastic approach to the receptivity problem



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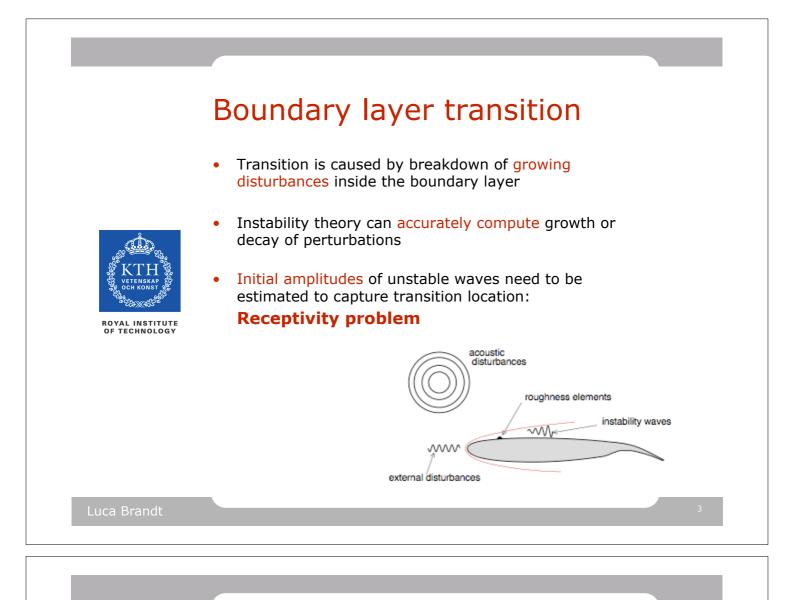
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- Introduction & Background
  - Receptivity problem
  - Motivation for stochastic approach
- Stochastic initial condition
  - By-pass transition
    - Realizability of optimal disturbances
    - Comparison with optimal IC
- Stochastic forcing
  - Uncorrelated forcing
  - Noise colouring
  - Results for boundary layers
- Conclusions



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# Stochastic Approach to Receptivity

Motivation



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- Predict the disturbance level for initial and external conditions, expected or modeled
- Estimate the realizability of optimal disturbances
- Robustness of deterministic results

Use a stochastic approach assuming a statistic description of external perturbations

# Problem formulation

• Linear discrete governing equations

$$\dot{q} = \mathcal{A}q + f u(t), \quad q(x, t = 0) = q_0.$$



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- Covariance of the flow defined as 
$$P(x,x',t) = \mathrm{cov}(q(x,t),q(x',t)) = \langle qq^H \rangle$$

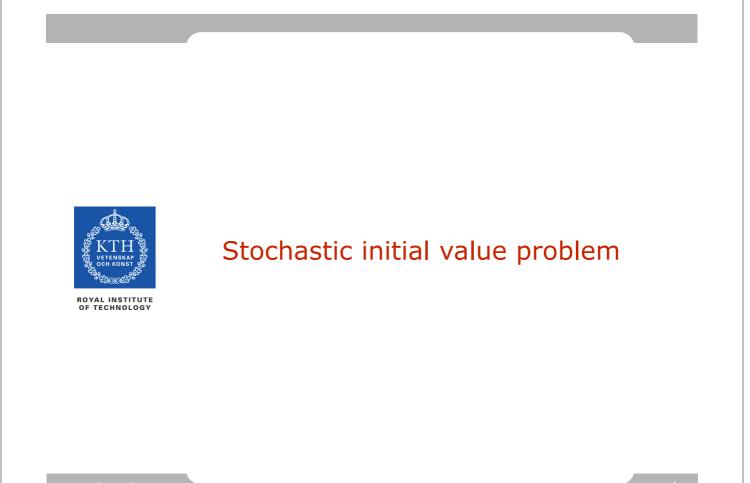
• Lyapunov equation for evolution of  ${\boldsymbol{P}}$ 

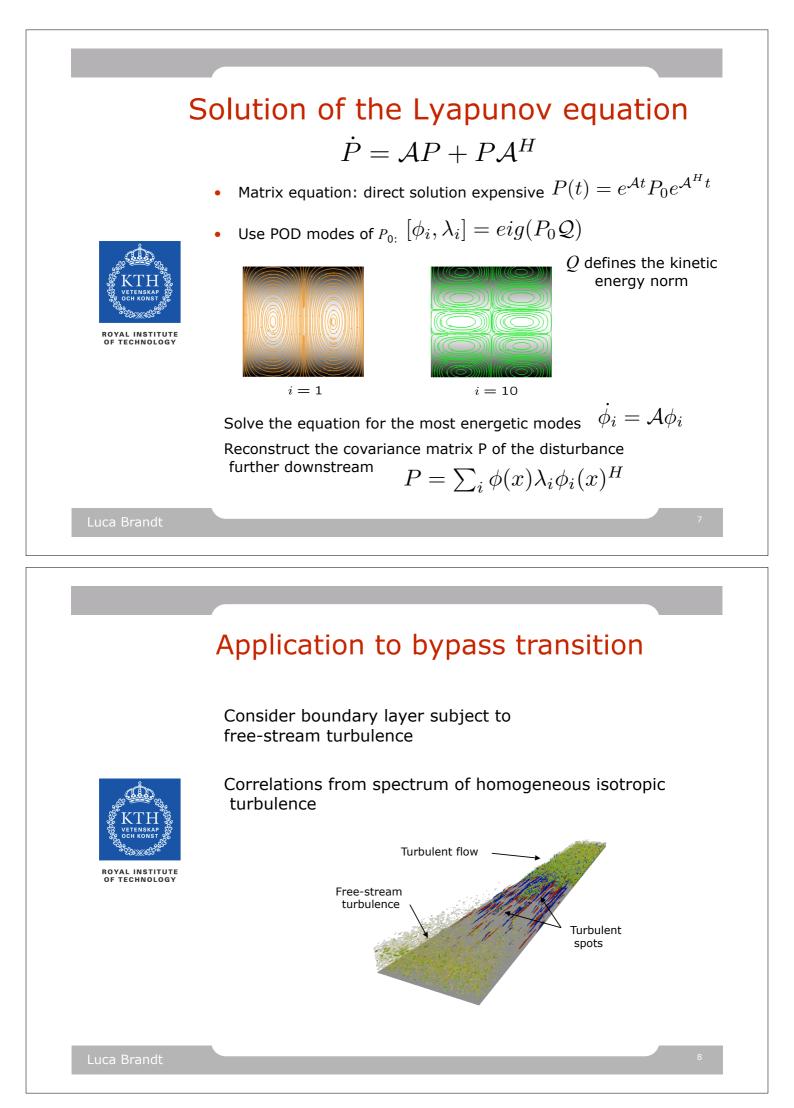
$$\dot{P} = \mathcal{A}P + P\mathcal{A}^H + M, \quad P(0) = P_0$$

*Po,* the covariance of the initial condition, and M, covariance of the external forcing, are modeled.

$$P_0 = \langle q_0 q_0^H \rangle; \ M = \langle f f^H \rangle; \ \langle u(t_1)u(t_2) \rangle = \delta(t_1 - t_2)$$

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### Disturbance description

#### Define covariance of initial free-stream perturbation:

Von Karman spectrum of homogeneous isotropic turbulence



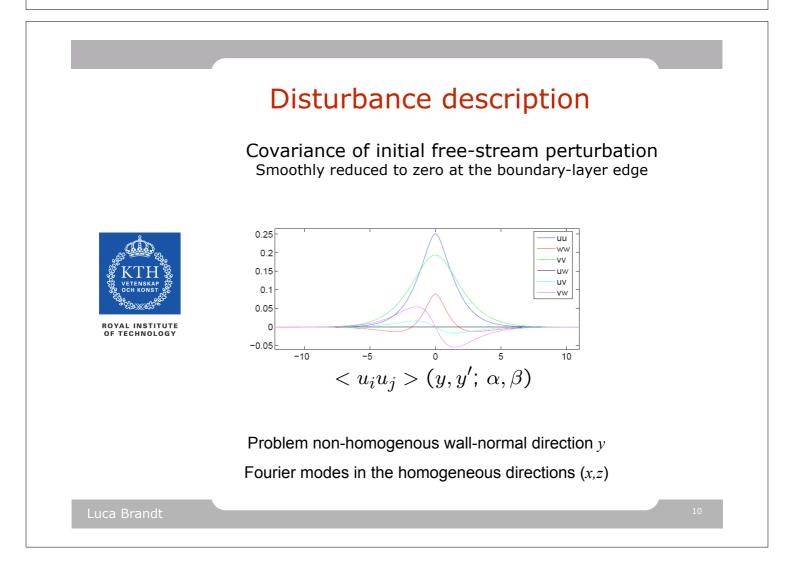
$$E(k) = \frac{2}{3} \frac{a(kL)^4}{(b+(kL)^2)^{17/6}} Lq$$

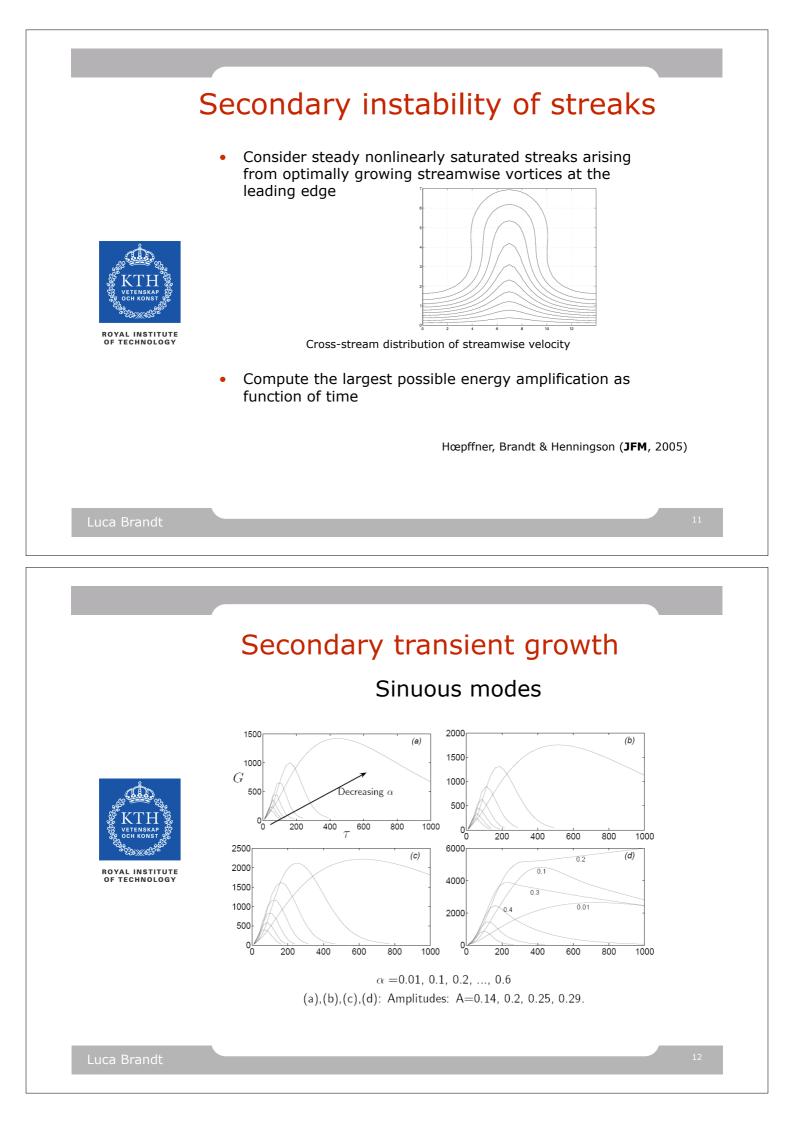
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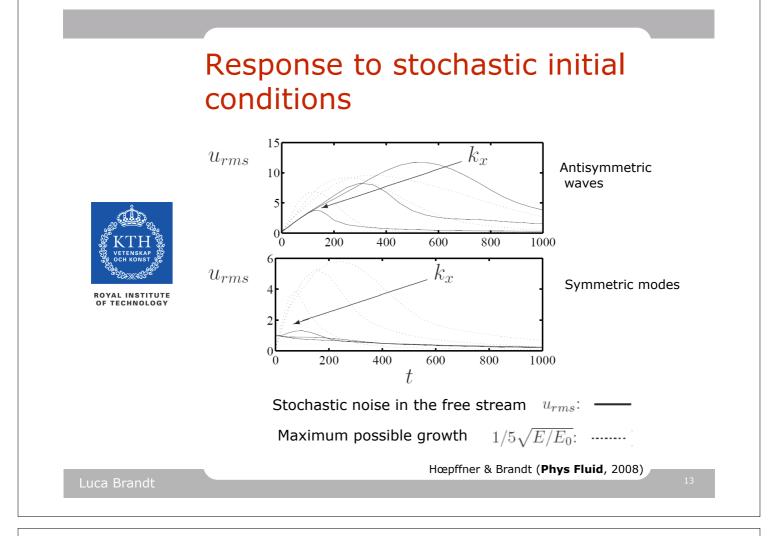
Fourier transform of two-point velocity correlation

$$< u_i u_j > = \frac{E(k)}{4\pi k^2} \left( \delta_{ij} - \frac{k_i k_j}{k^2} \right)$$











# Stochastic forcing

Steady-state Lyapunov equation:  $0 = \mathcal{A}P + P\mathcal{A}^H + M$ 



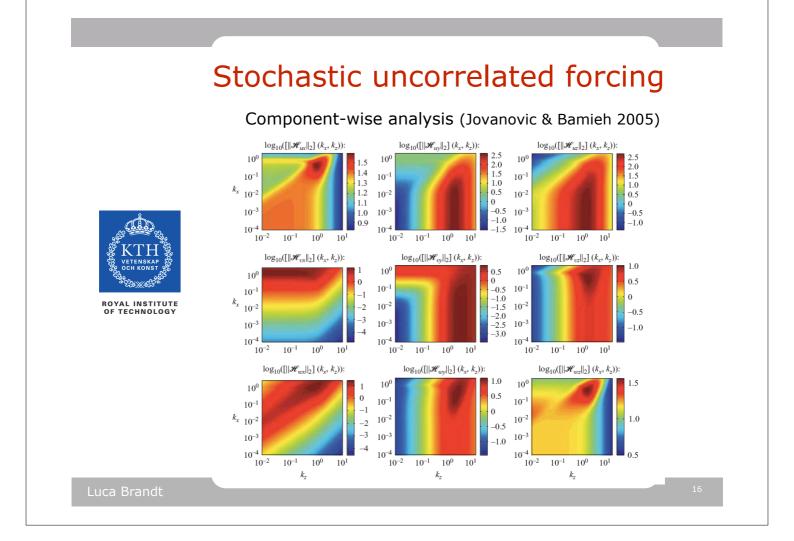
• Uncorrelated white noise  $M = \langle f f^H 
angle = \mathbf{I}$ 

Farrel & Ioannou, Jovanovic & Bamieh

• Spatially correlated white noise in time Hoepffner et al, Chevalier et al

Colored noise

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## Stochastic time-correlated noise

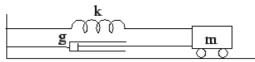
Lyapunov equation assumes white noise



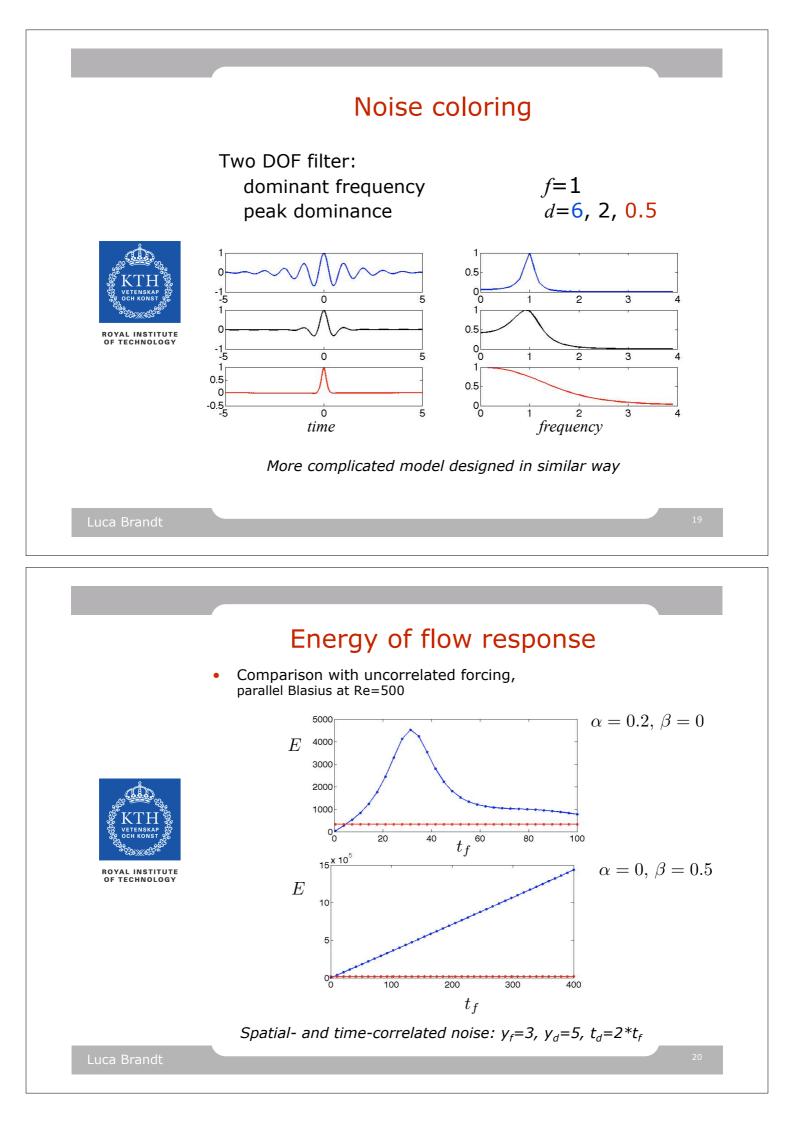
$$\begin{pmatrix} \dot{q} \\ \dot{w} \end{pmatrix} = \begin{pmatrix} \mathcal{A} & f \\ 0 & F \end{pmatrix} \begin{pmatrix} q \\ w \end{pmatrix} + \begin{pmatrix} 0 \\ \mathbf{I} \end{pmatrix} u(t)$$

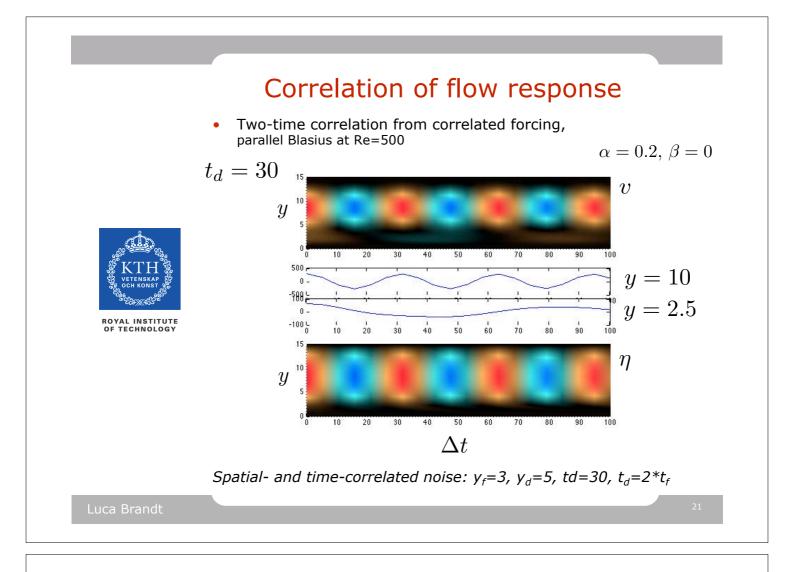
Time-correlated noise obtained by augmented system

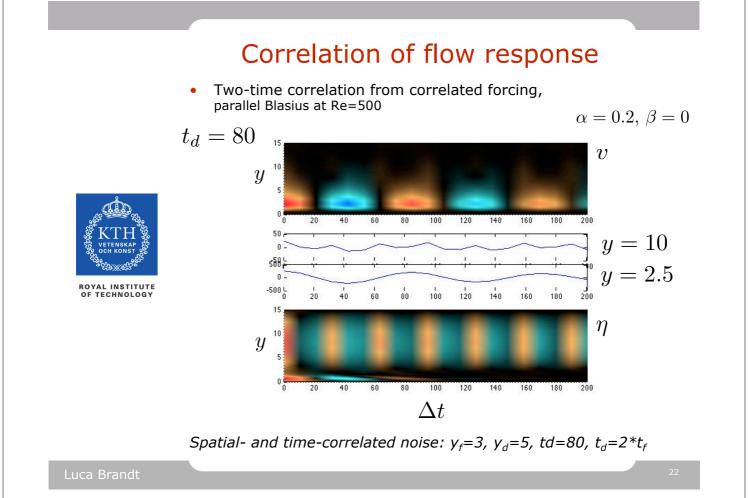
*F* filter for white noise: determines the forcing features  $2 \times 2$  system with complex conjugate eigenvalues

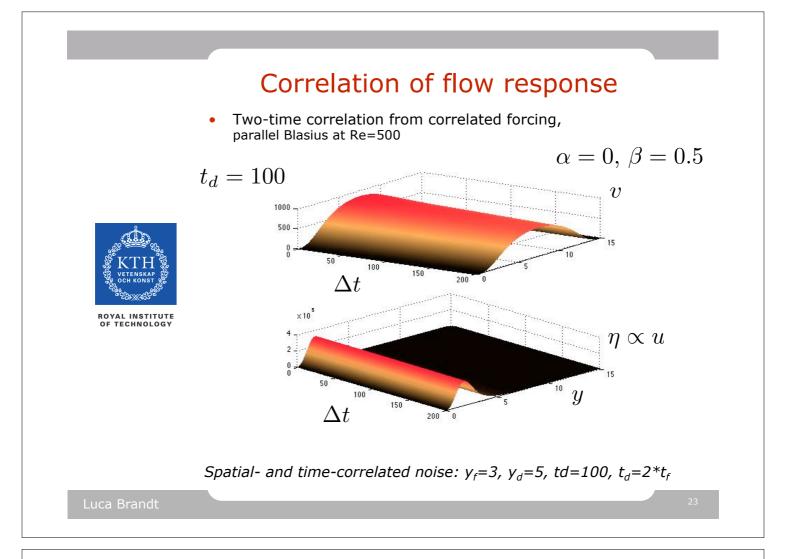


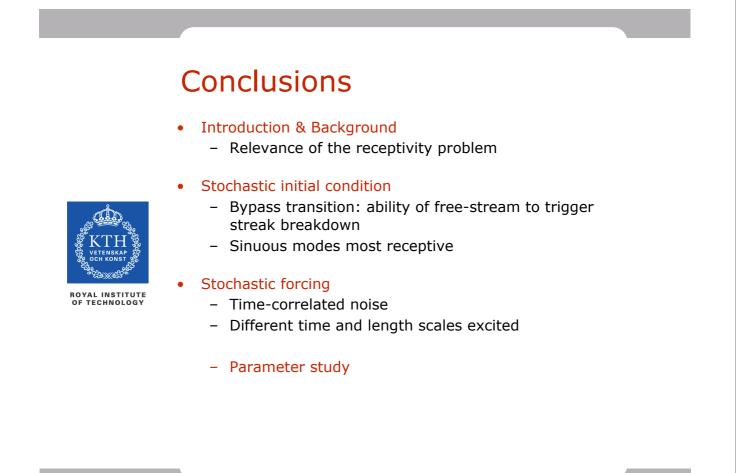
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